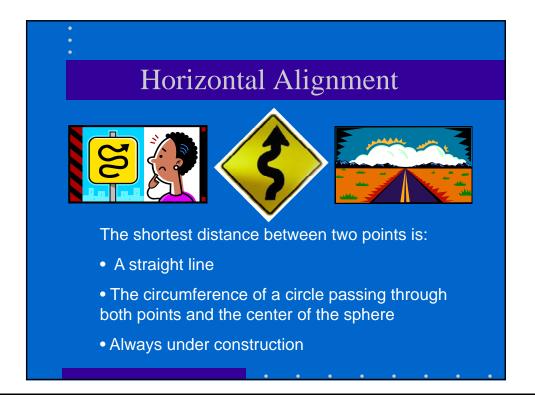
## Horizontal Alignments and Horizontal-Vertical Coordination

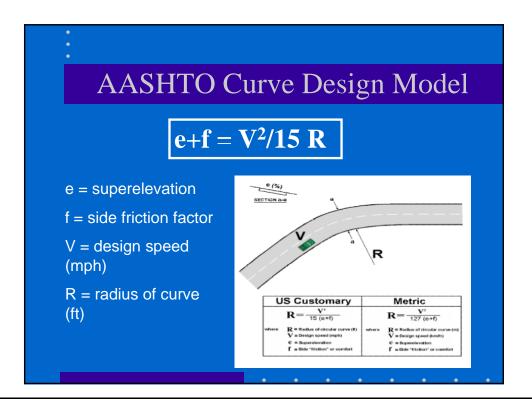




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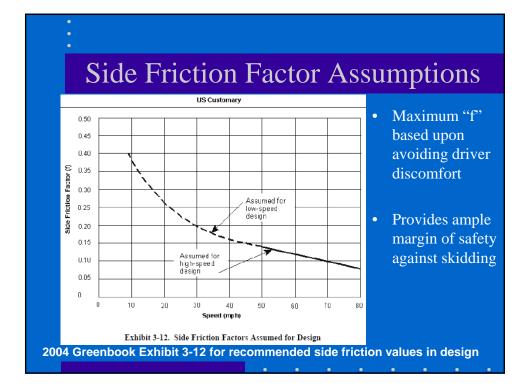
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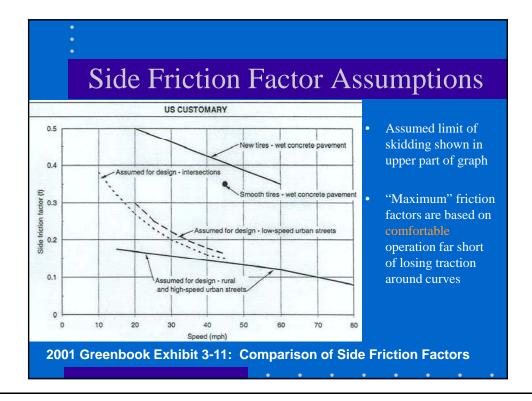




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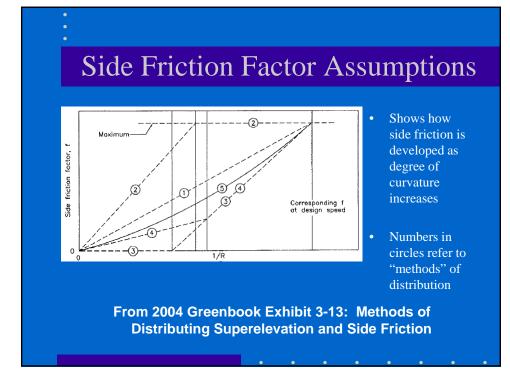


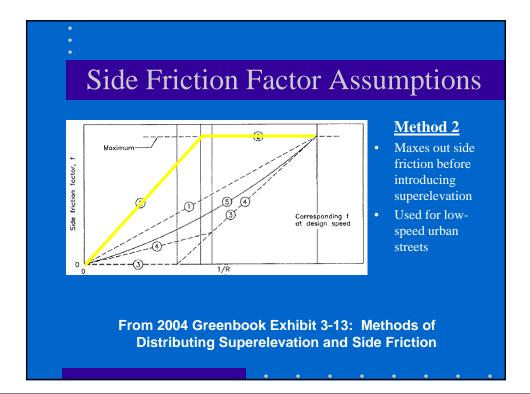


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## Horizontal Alignments and Horizontal-Vertical Coordination

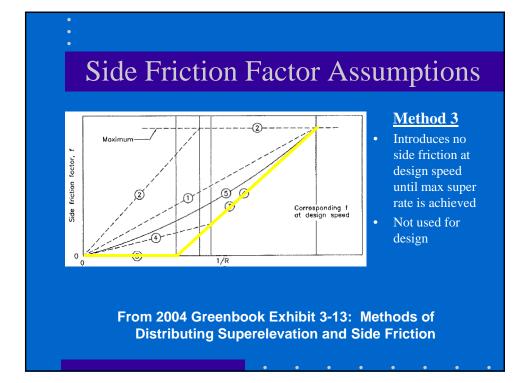


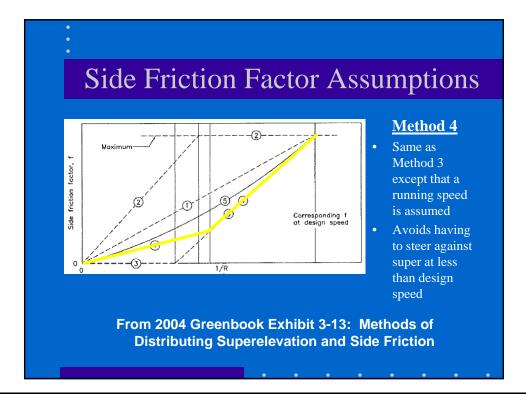


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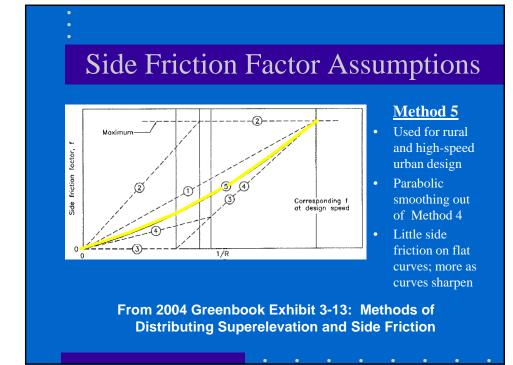


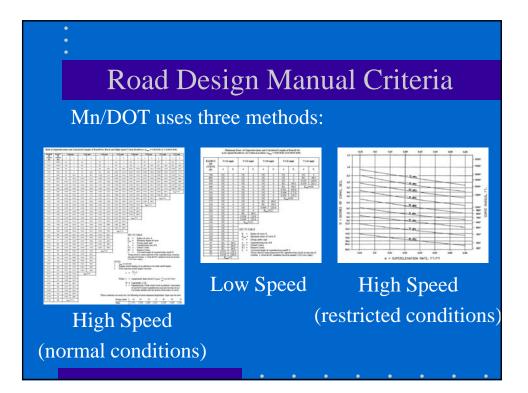


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## Horizontal Alignments and Horizontal-Vertical Coordination



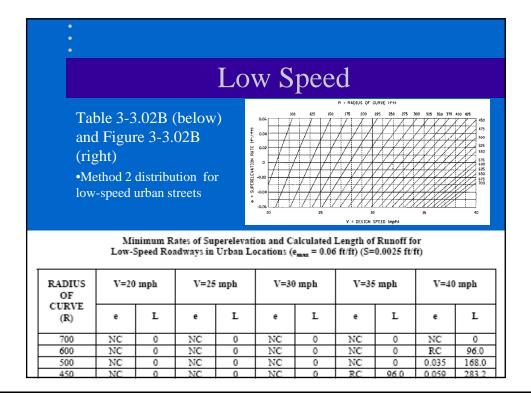


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## Horizontal Alignments and Horizontal-Vertical Coordination

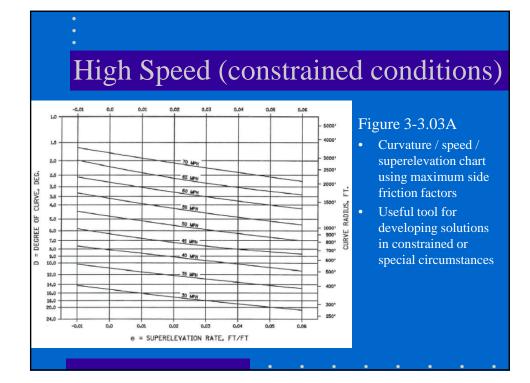
High Speed (normal conditions)																	
Table 3-3.02A (below) and Figure 3-3.02A (right) •Method 5 distribution for rural and high-speed urban design Rate of Superelevation and Calculated Length of Runoff for Rural and High-Speed Urban Roadways (e <sub>max</sub> = 0.06 ft/ft) (S = 0.0025 ft/ft)																	
DEGREE	RADIUS	V=40 mph		V=45 mph		V=50 mph		V=55 mph		V=60 mph		V=65 mph		V=70 mph		V=75 mph	
OF CURVE (D)	OF CURVE (R)	•	L	•	L		L	•	L	•	L	•	L	•	L	•	L
0°15'	22918	NC	0														
0°30'	11459	NC	0	RC	96.0	RC	96.0	RC	96.0								
0°45'	7639	NC	0	NC	0	RC	96.0	RC	96.0	0.021	100.8	0.023	110.4	0.025	124.8	0.029	139.2
1°00*	5730	NC	0	RC	96.0	RC	96.0	0.023	110.4	0.027	129.6	0.030	144.0	0.033	158.4	0.037	177.6
1°15	4584	RC	96.0	RC	96.0	0.024	115.2	0.028	134.4	0.032	153.6	0.035	172.8	0.040	192.0	0.044	211.2
1°30'	3820	RC	96.0	0.024	115.2	0.028	134.4	0.032	153.6	0.037	177.6	0.041	196.8	0.045	220.8	0.051	244.8
1°45'	3274	0.023	110.4	0.027	129.6	0.031	148.8	0.036	172.8	0.041	196.8	0.045	220.8	0.051	244.8	0.056	268.8
2°00'	2865	0.025	120.0	0.030	144.0	0.085	168.0	0.040	192.0	0.045	216.0	0.049	235.2	0.055	264.0	0.059	283.2
2°15	2546	0.028	134.4	0.033	158.4	0.038	182.4	0.043	206.4	0.048	230.4	0.053	254.4	0.057	273.6	0.060	288.0



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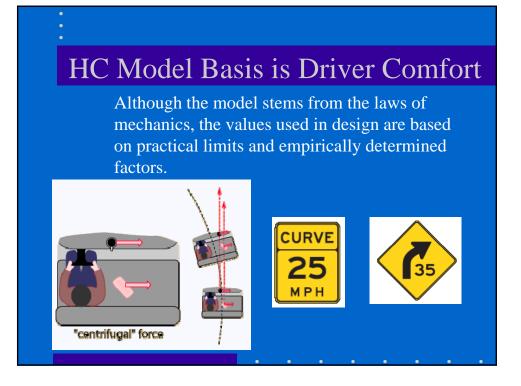
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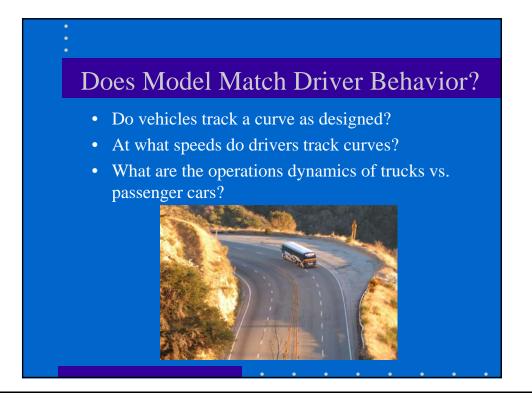


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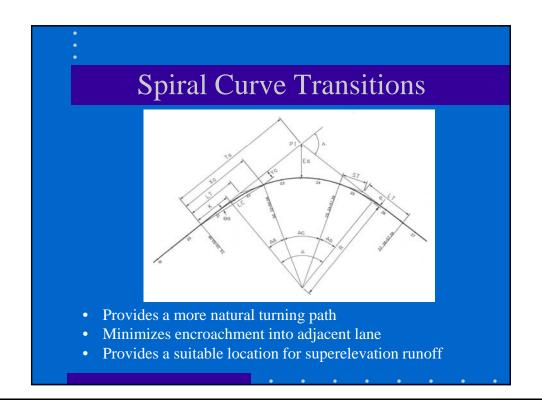




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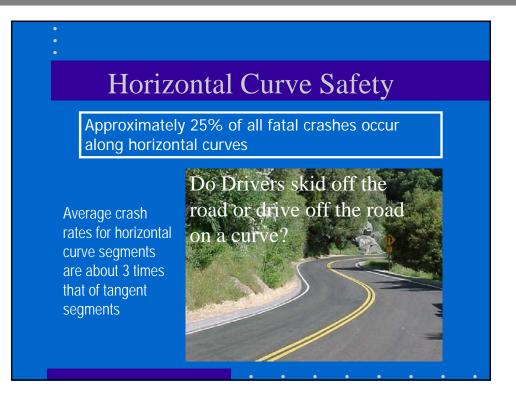
#### **Off-Tracking on Horizontal Curves** Actual Vehicle Path Does Not Follow a Perfect Circle Driver tracks a 'critical radius' sharper than that of the curve just past the PC Drivers 'Overshoot' (track a path sharper Curvature (1/km) cal radius, R . < R than the radius) Driver path is spiral **Overshoot behavior** is independent of Time (s) speed Figure D-2. Relationship between roadway curvature and travel path curvature in a tangent-to-curve transition design.

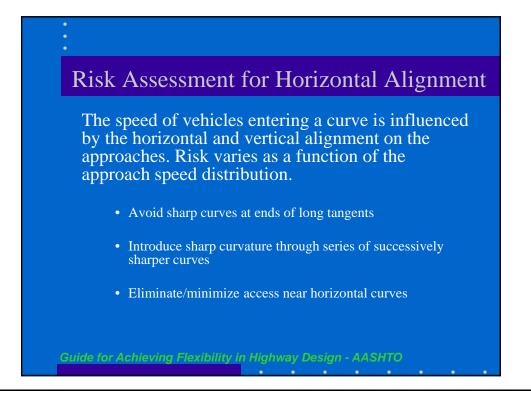


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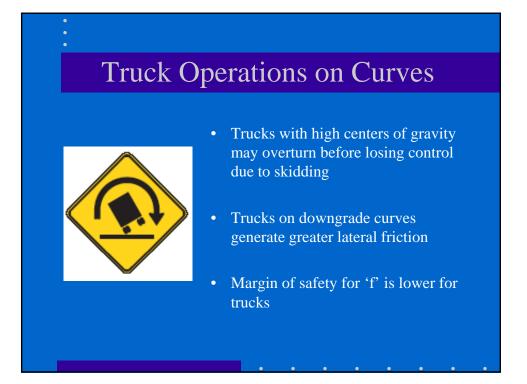


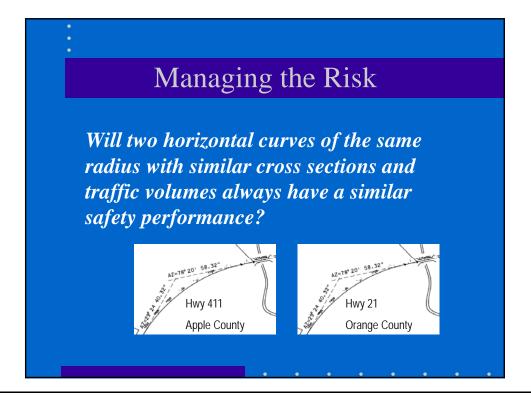


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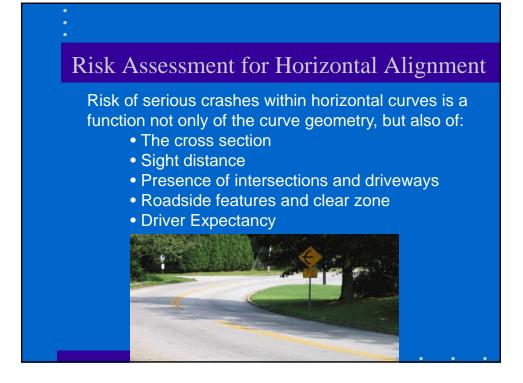
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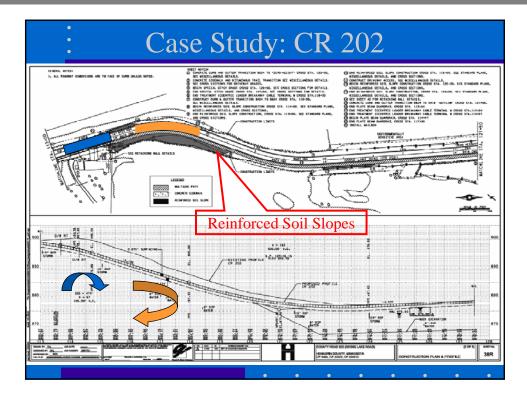
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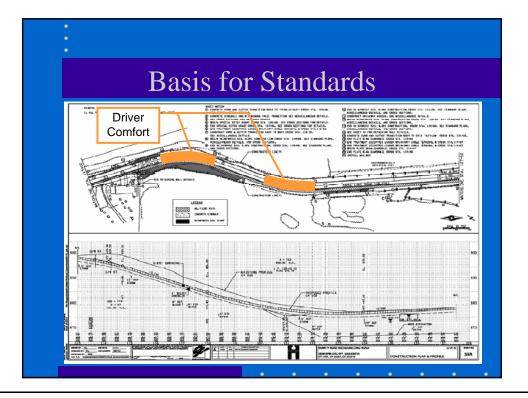




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